

INFORMATION DISCLOSURE CITATION FEB 5 2001
IN AN APPLICATIONAPPLICANT: Robert K. Jenner, *et al.*

FILING DATE: 09/21/2000

GROUP: 2812

3726

U.S. PATENT DOCUMENTS

EXAMINER INITIAL		DOCUMENT NUMBER	DATE	NAME	CLASS	SUB-CLASS	FILING DATE IF APPROPRIATE
<i>MJ</i>	AA	5,388,119	02/07/1995	Cronin, <i>et al.</i>	372	69	
<i>I</i>	AB	5,745,624	04/28/1998	Chan, <i>et al.</i>	385	91	
<i>MJ</i>	AC	6,103,988	08/15/2000	Kim	219	121.63	
	AD						
	AE						
	AF						
	AG						

FOREIGN PATENT DOCUMENTS

		DOCUMENT NUMBER	DATE	COUNTRY	CLASS	SUB-CLASS	TRANSLATION YES	NO
<i>MJ</i>	AH	EP 0 030 617 A2	05 NOV 1980	EP	G02B	7/26		X
Concise Explanation: this reference shows a filter splicer								
<i>MJ</i>	AI	WO 00/41021	13 JUL 2000	PCT	G02B	6/42	X	
	AJ							
	AK		/					

OTHER DOCUMENTS (Including Author, title, Date, Pertinent Pages, Etc.)

<i>MJ</i>	AL	Goldfarb, Michael; Speich, John E., "Design of a Minimum Surface-Effect Three Degree-of-Freedom Micromanipulator," Proceedings of the 1997 IEEE International Conference on Robotics and Automation, Albuquerque, New Mexico – April 1997.
<i>MJ</i>	AM	Goldfarb, Michael; Speich, John E., "Eliminating Non-Smooth Nonlinearities With Compliant Manipulator Design." Proceedings of the American Control Conference, Philadelphia, Pennsylvania – June 1998.
<i>MJ</i>	AN	Heinen, Simon; Aymon, Cédric; Bottinelli, Stefano; Clavel, Reymond, "Articulated Structures With Flexible Joints Dedicated to High Precision." Département de Microtechnique, Institute de Systèmes Robotiques (DMT-ISR), Swiss Federal Institute of Technology Lausanne (EPFL), EPFL CH-1015, Lausanne, Switzerland.
<i>MJ</i>	AO	Speich, John E.; and Goldfarb, Michael, "A Three Degree-of-Freedom Flexure-Based Manipulator for High Resolution Spatial Micromanipulation." Part of the SPIE Conference on Microrobotics and Micromanipulation, Boston, Massachusetts, November 1998. SPIE Vol. 3519.

EXAMINER

Marc Jenner

DATE CONSIDERED

August 23, 2002